

THE SHAPE OF AN IMAGE: A STUDY OF MAPPER ON IMAGES

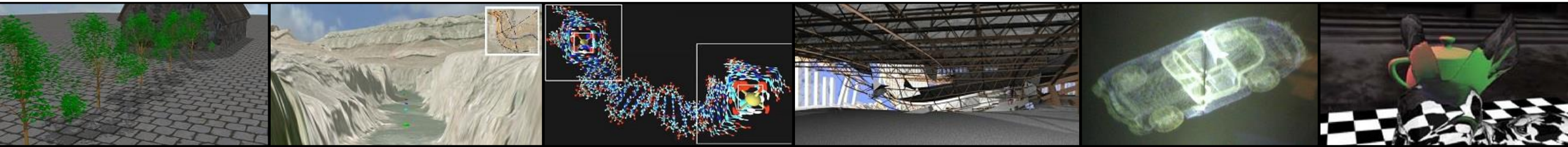


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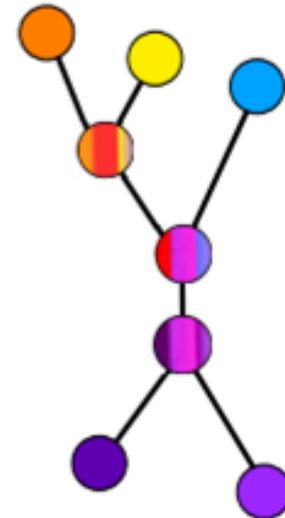
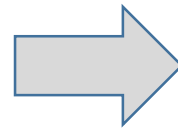
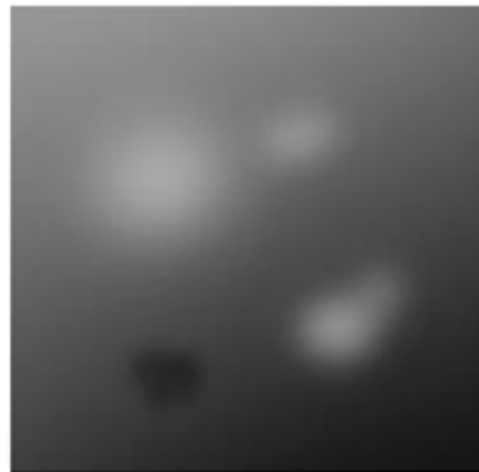
MOTIVATION

Scalar function is defined on planar domain

We would like to extract a topological fingerprint

WHY?

Topological fingerprint as a feature vector is translation, rotation, and resolution invariant

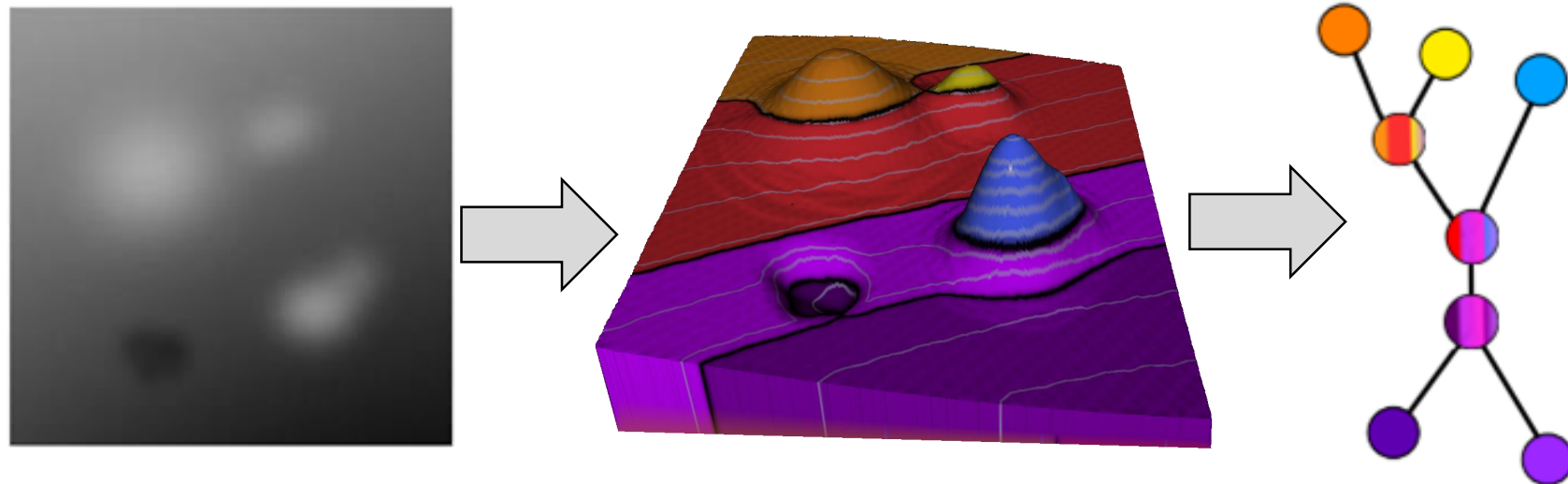


PROCESS OVERVIEW

Convert the scalar field into a landscape

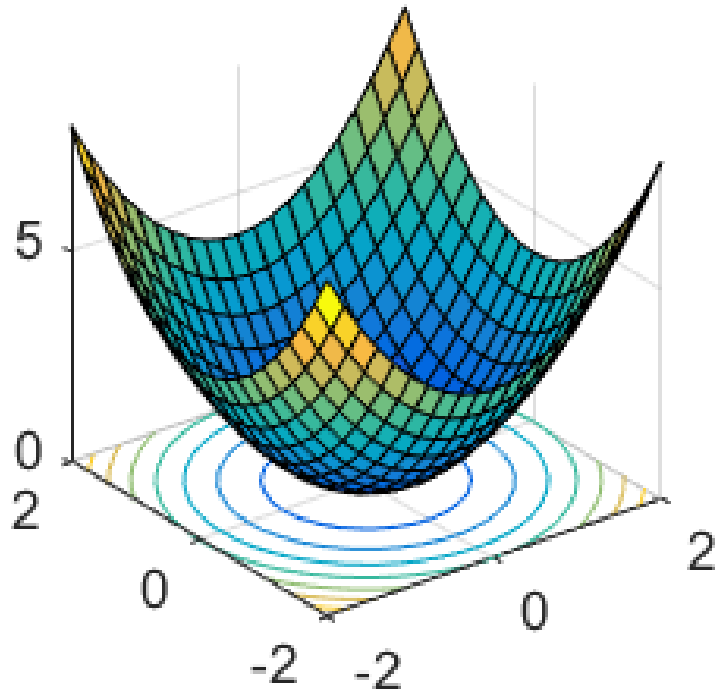
Segment the domain into topological regions by value

Use the relationship between those regions to describe the topology of the domain

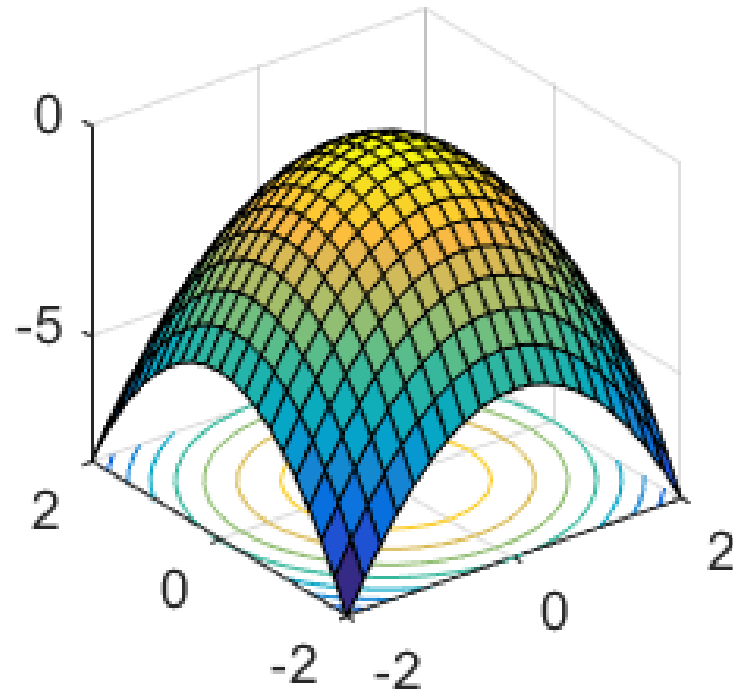


TOPOLOGICAL FEATURES

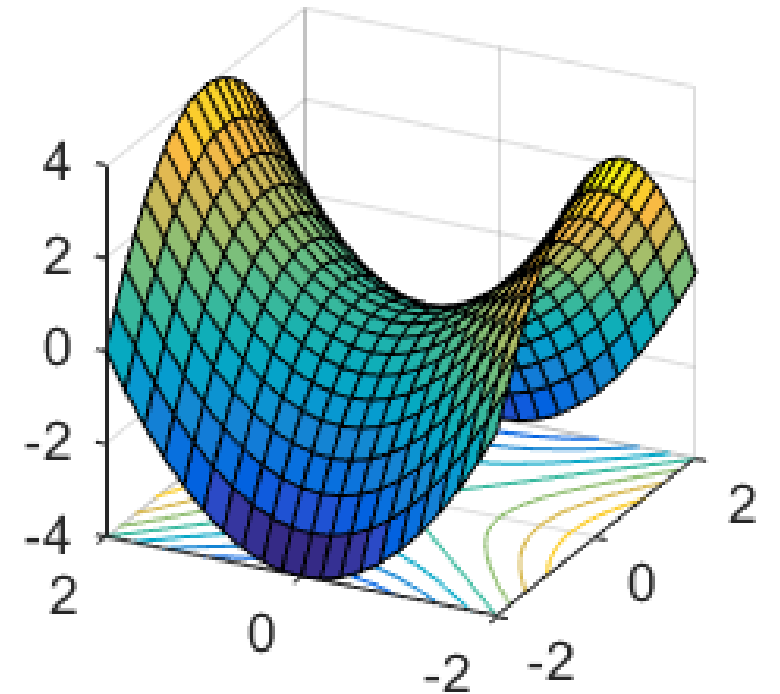
local min



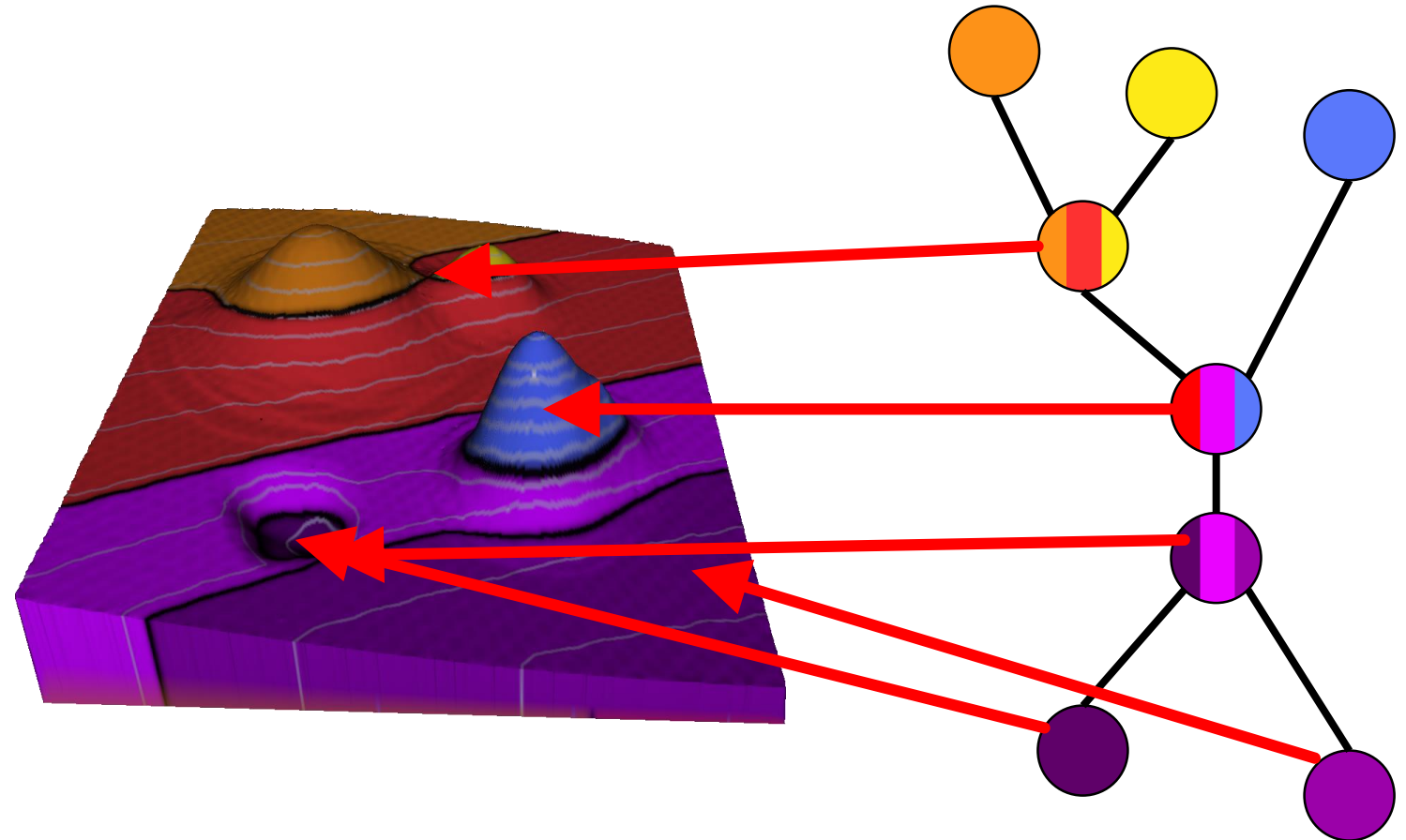
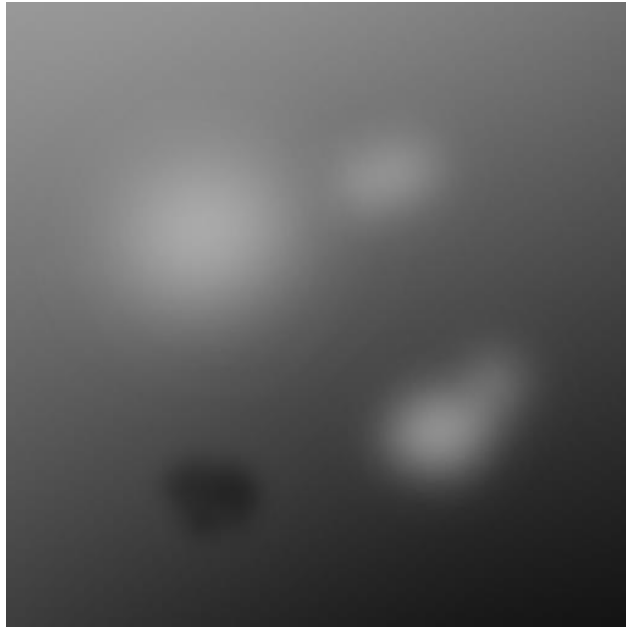
local max



saddle point



TOPOLOGY OF THE FIELD (CONTOUR TREE)



MAPPER

Computation of approximate topology

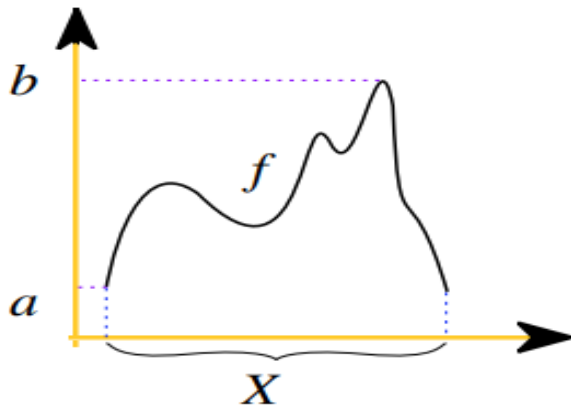
More flexible and robust implementation & runs
faster than contour tree

Ability to control approximation resolution through
modifying the “cover”



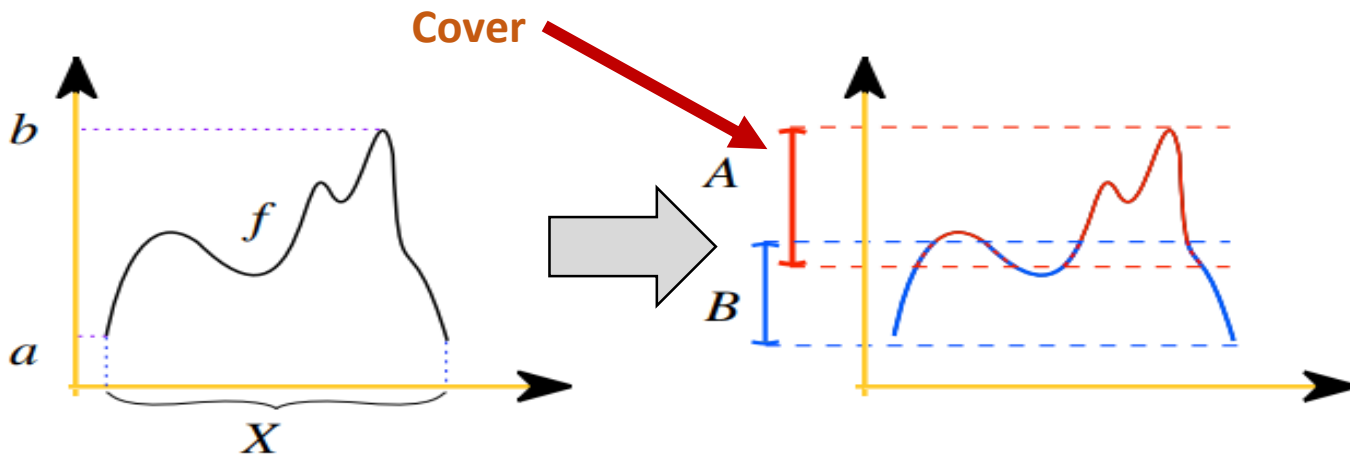
THE CONSTRUCTION OF MAPPER ON A 1D FUNCTION

Consider a scalar function $f : X \rightarrow [a,b]$



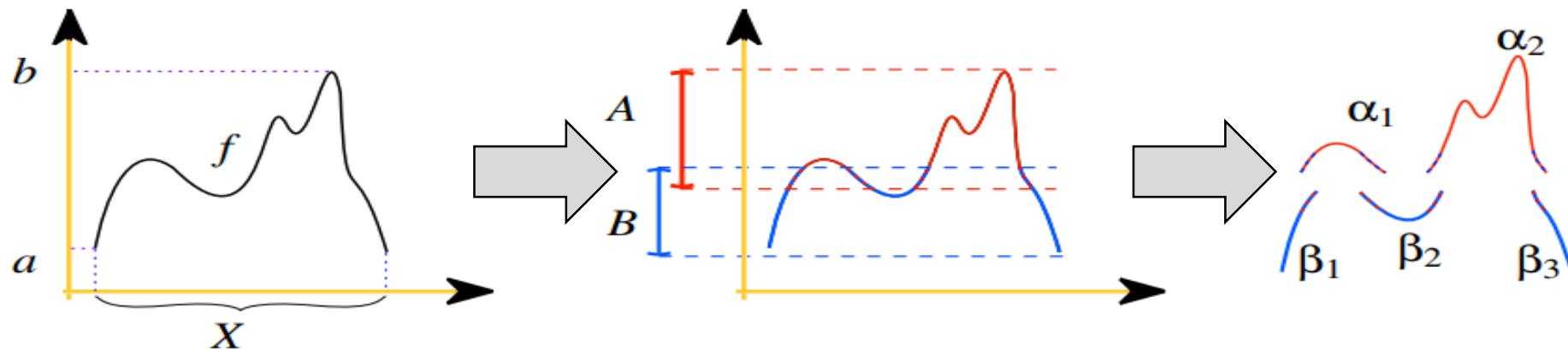
THE CONSTRUCTION OF MAPPER ON A 1D FUNCTION

The range $[a,b]$ is covered by the two intervals A,B



THE CONSTRUCTION OF MAPPER ON A 1D FUNCTION

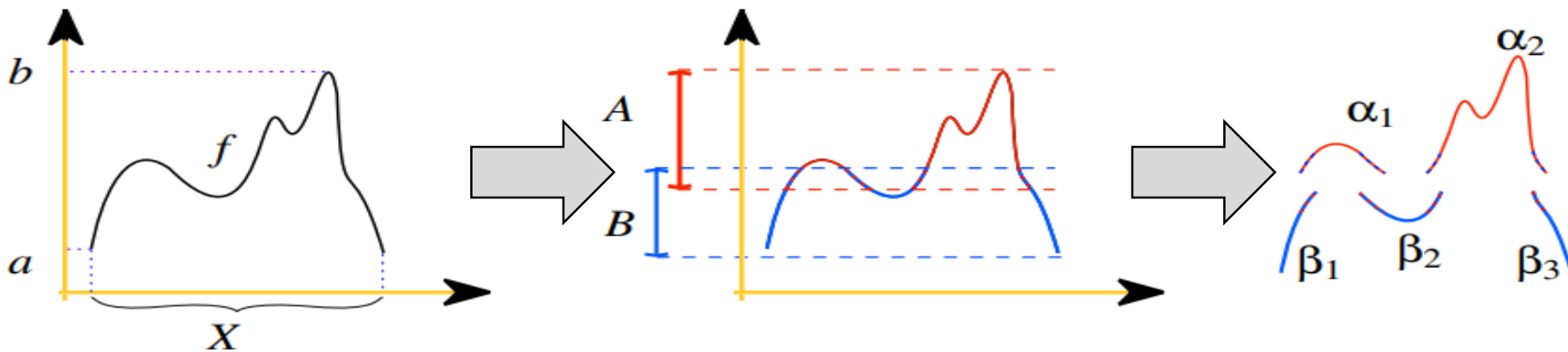
This gives a decomposition of the domain the domain X



THE CONSTRUCTION OF MAPPER ON A 1D FUNCTION

Inverse of A consists of 2 connected components α_1 and α_2

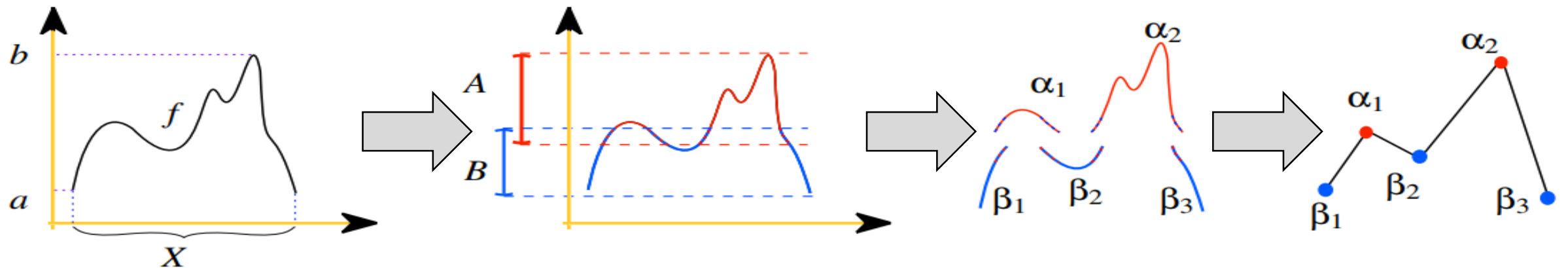
Inverse of B consists of 3 connected components β_1, β_2 and β_3



THE CONSTRUCTION OF MAPPER ON A 1D FUNCTION

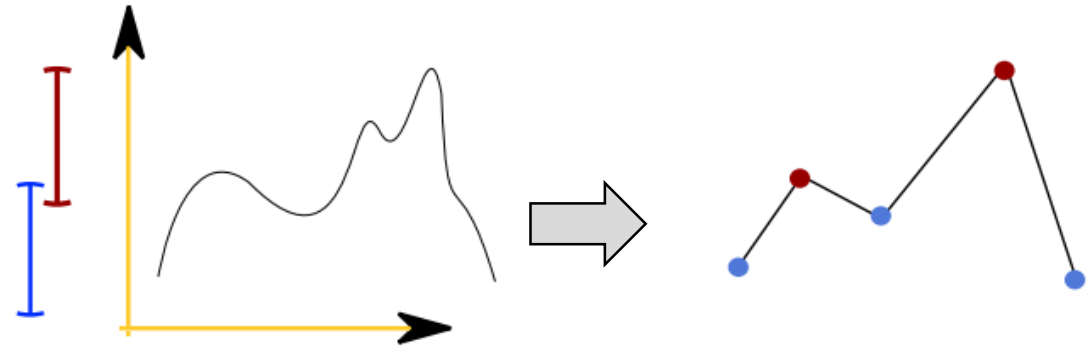
A **nodes** represents each connected component

An **edge** is inserted whenever 2 connected components overlap

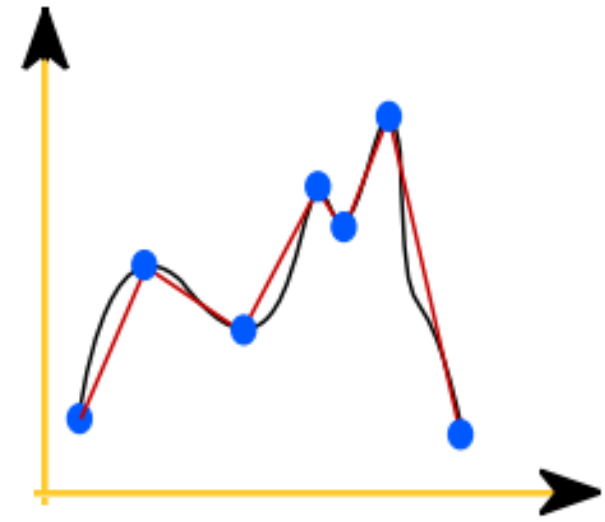
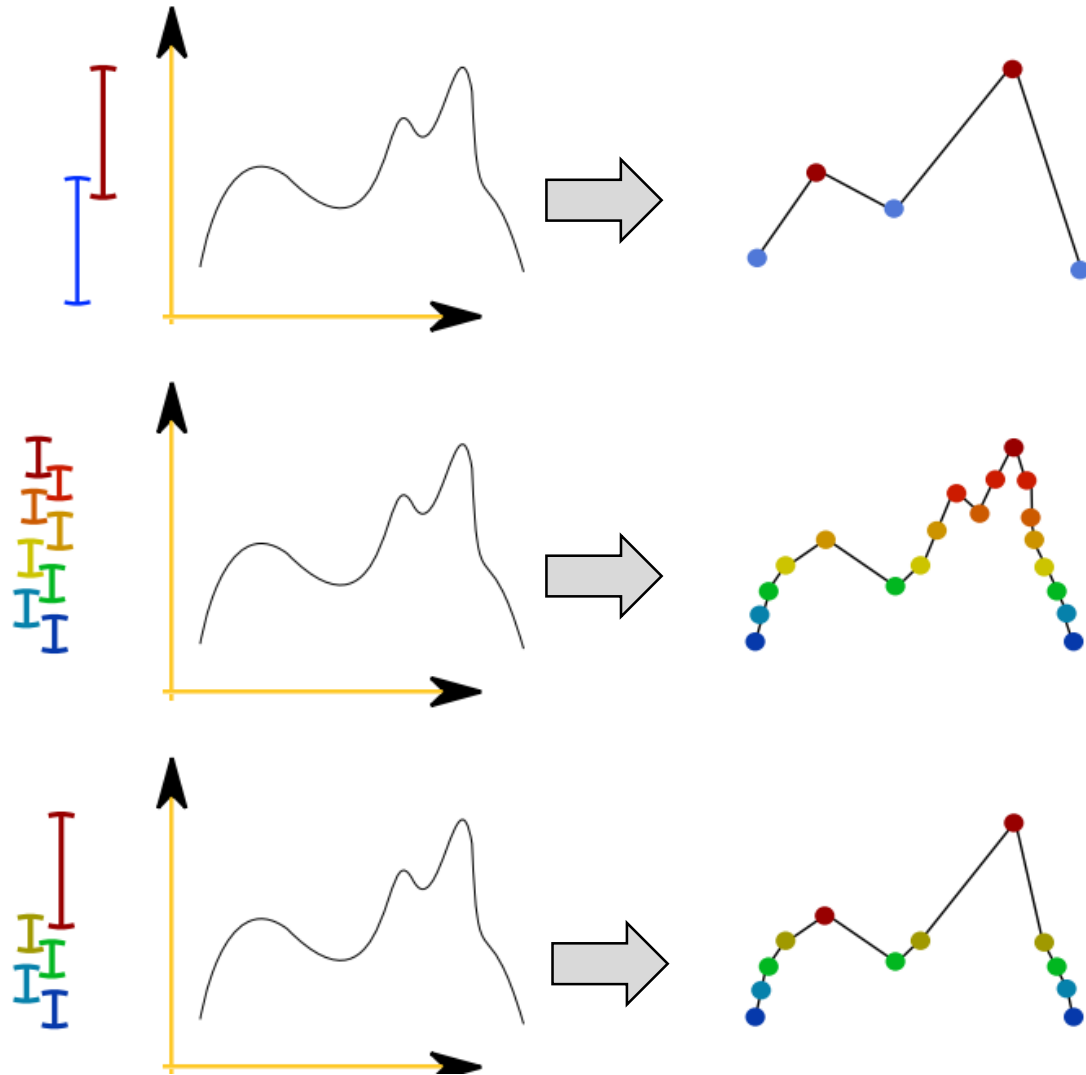


MAPPER RESOLUTION

The construction of mapper depends on the cover chosen for the range $[a,b]$ of the scalar function.



COMPARISON TO CONTOUR TREE

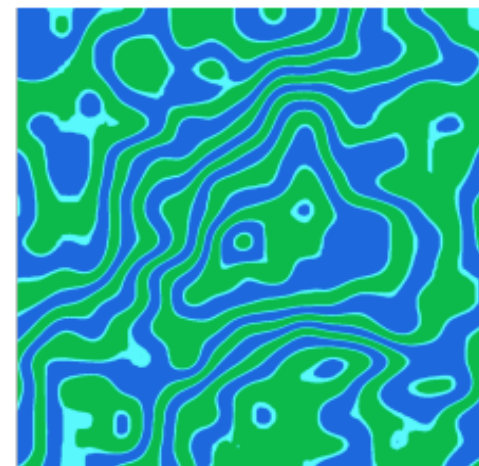
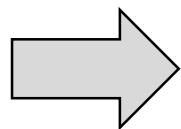


The contour tree of a 1d function.



COMPUTATION OF MAPPER ON IMAGES

Covers are first extracted as even and odd covers, plus overlap used later.



Input

Even

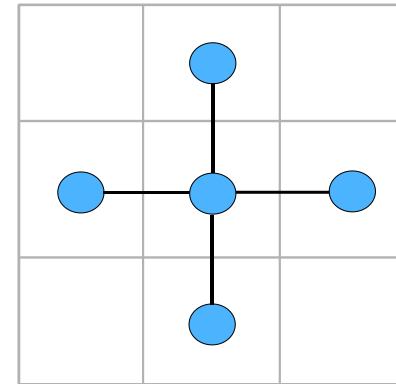
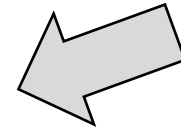
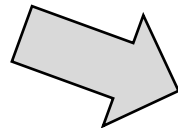
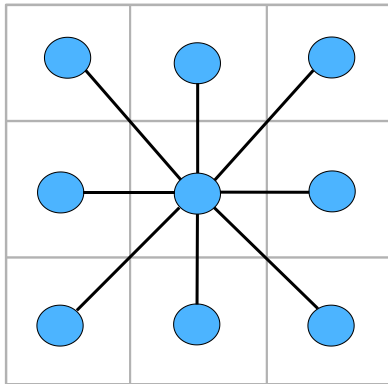
Odd

Overlap



FINDING VERTICES

Covers are converted to graphs using 1 of 2 schemes, and connect components identified using either DFS or BFS

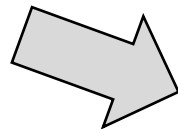


FINDING EDGES

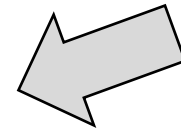
Pixels from overlapping regions cause edges between connected components in adjacent covers



Even



Overlap



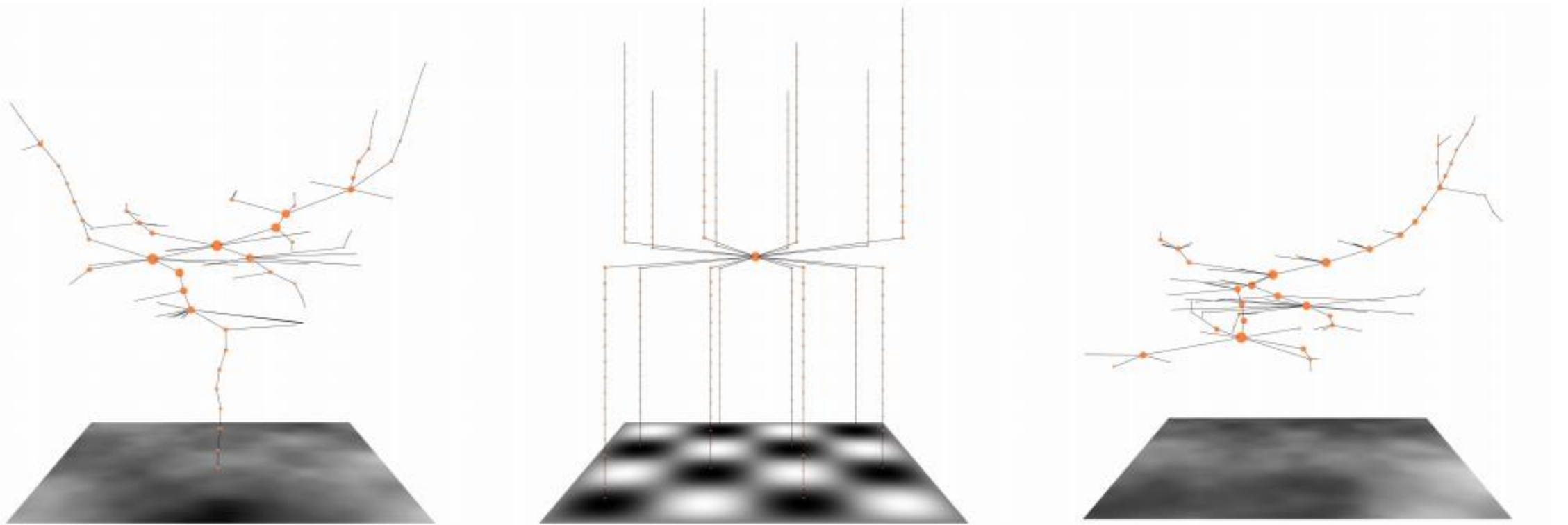
Odd



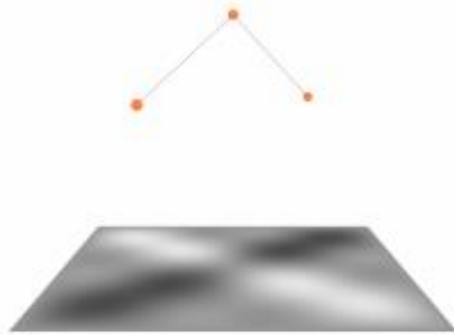
RESULTS



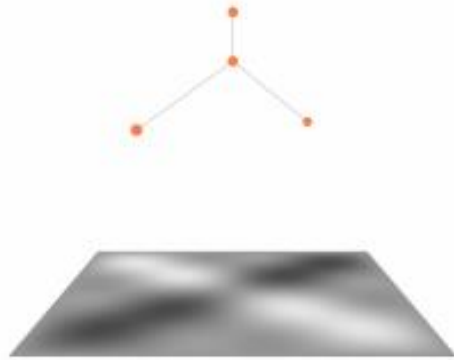
MAPPER ON IMAGES



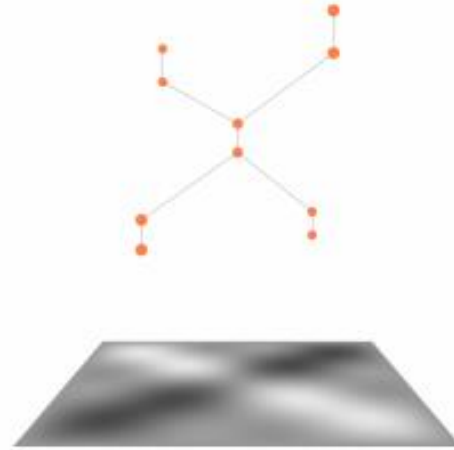
ADJUSTING MAPPER RESOLUTION



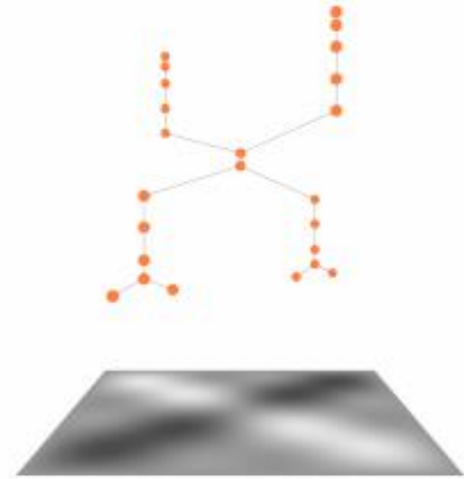
2 cover slices



4 cover slices



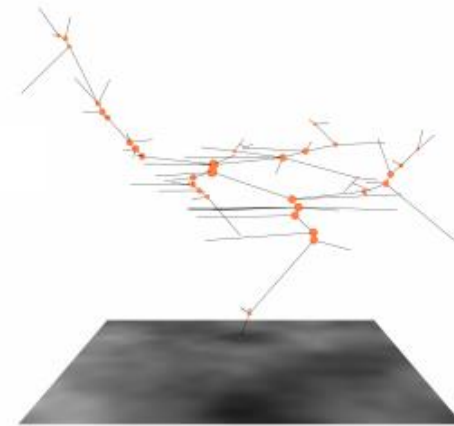
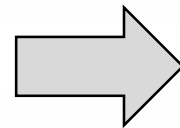
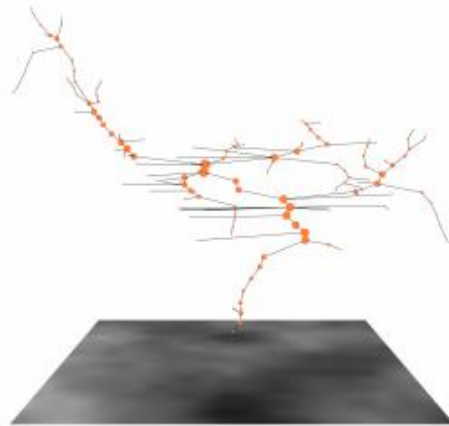
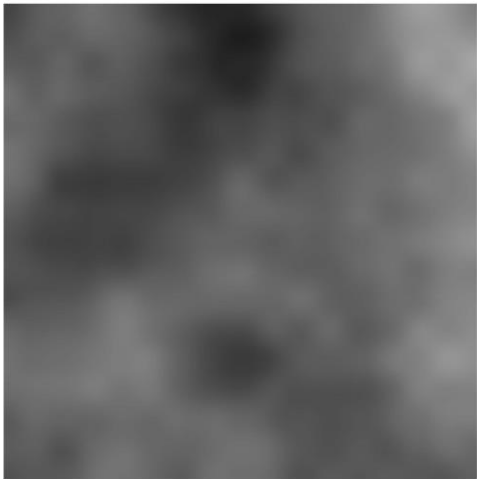
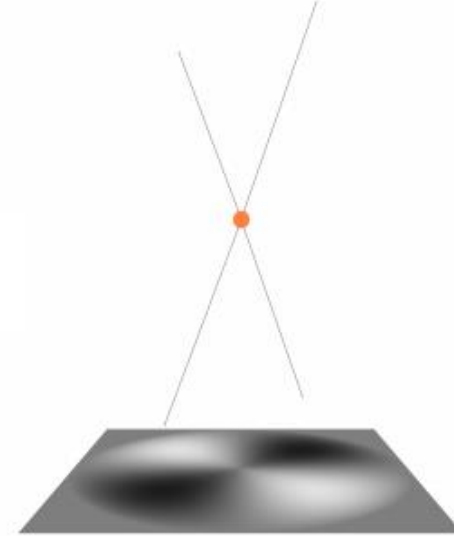
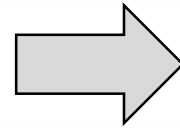
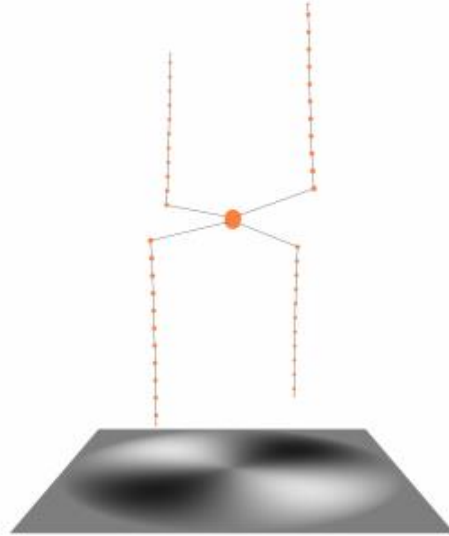
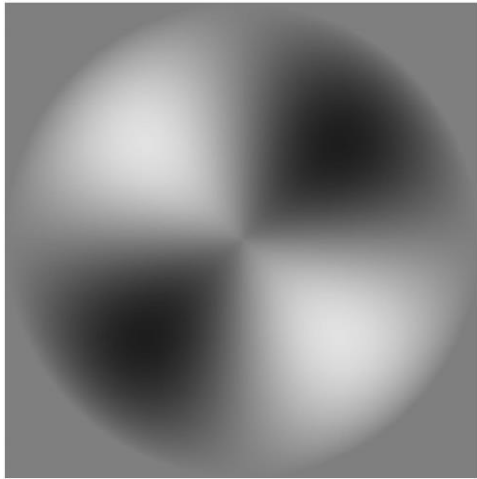
8 cover slices



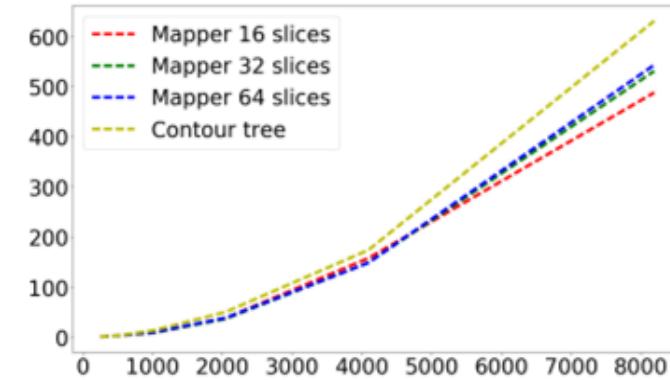
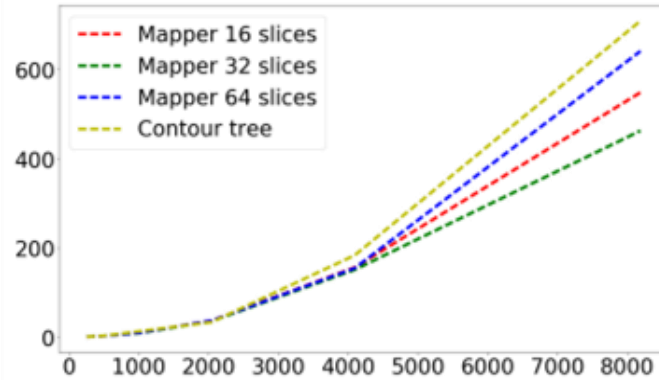
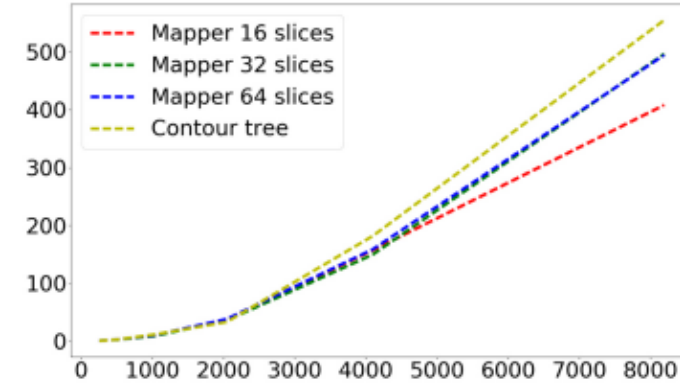
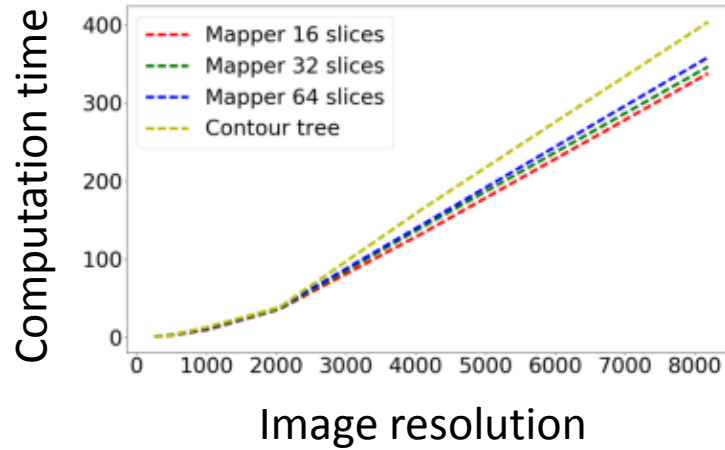
16 cover slices



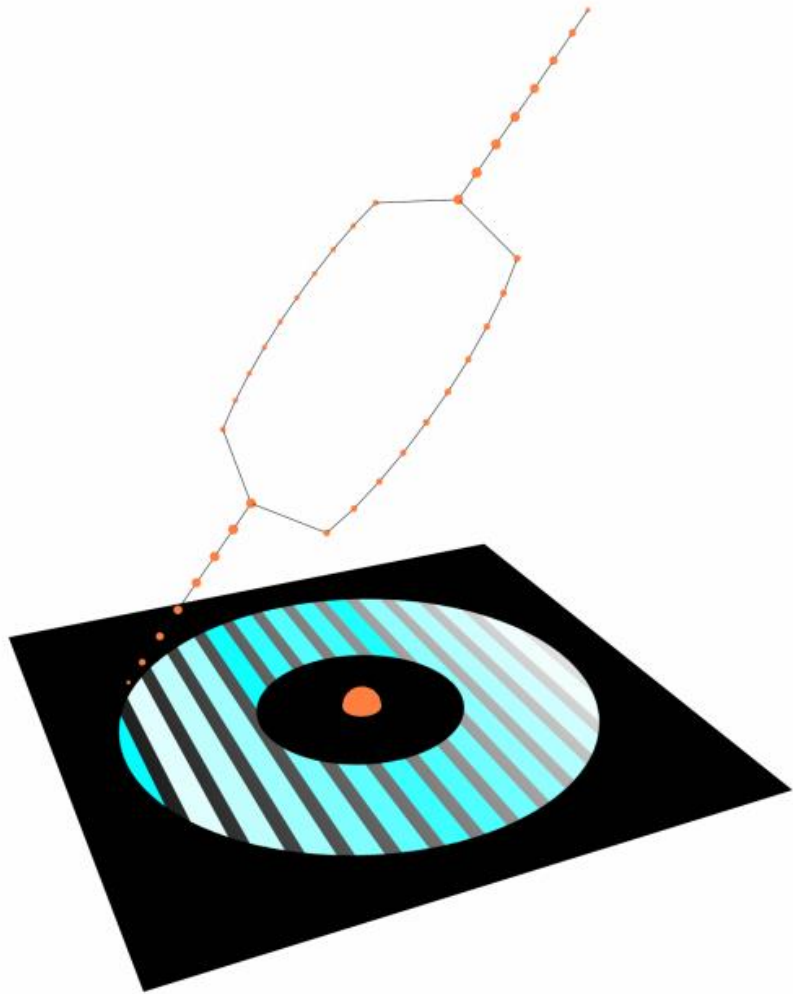
SIMPLIFICATION OF MAPPER GRAPHS



MAPPER PERFORMANCE ON 4 DIFFERENT IMAGES



ADDITIONAL RESULTS



CONCLUSIONS

Mapper on image is fast and flexible to compute

Topological fingerprint could serve as a good feature vector, given that it is translation, rotation, and image resolution invariant



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