## The Backpropagation Algorithm

MUSTAFA HAJIJ

## Perceptron



## Perceptron


b is called a bias term.

## Perceptron




## Training Perceptron

Given a collection of points $\left(x_{1}, y_{1}\right), \ldots .,\left(x_{n}, y_{n}\right)$ where
$x_{i}$ is a points in $R^{d}$ and $y_{i}$ is a label that takes values in $\{-1,+1\}$

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$x_{i}$ is a points in $R^{d}$ and $y_{i}$ is a label that takes values in $\{-1,+1\}$
We want to choose $w=\left[w_{1}, \ldots w_{d}\right]$ and b such that the hyperplane determined by the $w x+b=0$ separates the points $x_{i}$ according to their labels. In other words, we want to choose the plane $w x+b=0$ so that all points with positive sign on one side and all points with negative sign on the other side.

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As usual we have to define a cost function and a notion of error.

## General Gradient Decent Algorithm

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Outline :
(1) Initiate $w_{1}, \ldots, w_{d}$ randomly
(2) keep changing $w_{1}, \ldots, w_{d}$ until hopefully $f\left(w_{1}, \ldots, w_{d}\right)$ is minimal

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But how exactly do we change $w_{1}, \ldots, w_{d}$ ?

## General Gradient Decent Algorithm

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(2) Repeat until convergence :
(1) For every $i$ in range $(1, d)$ :

$$
\text { (1) } w_{i}:=w_{i}-q \frac{\partial f}{\partial w_{i}} \text { (here we do simultaneous update for the parameters } w_{i} \text { ) }
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$$

Gradient decent asserts that the values of the function $f$ when we update as described above are non-increasing :

$$
f\left(\text { old } w_{i}\right) \geq f\left(\text { new } w_{i}\right)
$$

## Training Perceptron

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$$
w^{T} x_{1}+b=w^{T} x_{2}+b=0
$$

Hence
$w^{T}\left(x_{1}-x_{2}\right)=0$
Hence the vector $w^{T}$ is orthogonal to $\left(x_{1}-x_{2}\right)$

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$$

Hence
$w^{T}\left(x_{1}-x_{2}\right)=0$
Hence the vector $w^{T}$ is orthogonal to $\left(x_{1}-x_{2}\right)$
Moreover, for any $x_{0}$ on the plane $w^{T} x+b=0$ we have

$$
b=-w^{T} x_{0}
$$

## Training Perceptron

$$
d=w^{T}\left(x^{\prime}-x_{0}\right)=w^{T} x^{\prime}-w^{T} x_{0}=w^{T} x^{\prime}+b
$$



## Training Perceptron

$$
d=w^{T}\left(x^{\prime}-x_{0}\right)=w^{T} x^{\prime}-w^{T} \mathbf{x}_{0}=w^{T} x^{\prime}+b
$$

So if we have a point and we want to see where it is located on with respect to the plan, then all we have to do is to plug it in the equation of the plane.


## Training Perceptron

Write

$$
d_{i}=y_{i}\left(w^{T} x_{i}+b\right)
$$

Where $\left(x_{i}, y_{i}\right)$ is a training example

[^0]

## Training Perceptron

## Define

$$
\operatorname{error}(w, b):=-\sum_{M} y_{i}\left(w^{T} x_{i}+b_{0}\right)
$$



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Where $M$ is the set of misclassified points


## Training Perceptron

Define

$$
\operatorname{error}(w, b):=-\sum_{M} y_{i}\left(w^{T} x_{i}+b_{0}\right)
$$

Where $M$ is the set of misclassified points

We want to apply gradient decent on the function $\operatorname{error}(w, b)$

$$
\begin{aligned}
& \frac{\partial \operatorname{error}(w, b)}{\partial w}=\sum_{M} y_{i} x_{i} \\
& \frac{\partial \operatorname{error}(w, b)}{\partial b}=\sum_{M} y_{i}
\end{aligned}
$$



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(1) Assign the weights $w$ randomly


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$$
\begin{aligned}
& w_{\text {new }}:=w_{\text {old }}-q \frac{\partial \operatorname{error}(w, b)}{\partial w} \\
& b_{\text {new }}:=b_{\text {old }}-q \frac{\partial \operatorname{error}(w, b)}{\partial b}
\end{aligned}
$$



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if the examples are linearly separable then the above model classifies the points


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Stochastic gradient decent


## Neural Network

Perceptron is the building block of a neural network. Clearly there are some data that cannot be classified using a single perceptron.

The idea of neural network is to stack together multiple layers of perceptrons in order to be able to learn more complicated functions
hidden layer


## Neural Network

Mathematically, a neural network is a function $f$ that takes $x$ as input and produces an output $y=f(x)$

## hidden layer



## Neural Network

Mathematically, a neural network is a function $f$ that takes $x$ as input and produces an output $y=f(x)$
The training of a neural network means to tune the weights in all layers so that the output of the function $f$ matches the label of $x$. The process of updating the weights for a feedforward neural network is called backpropagation.

## hidden layer



## Feedforward Neural Network

How do we compute a feedforward neural network on an input $x$ ?

## Feedforward Neural Network

Start with an input $x=a^{(0)}$. In the picture, this is represented by the first layer of nodes. We will call this layer 0 .

$$
x=a^{(0)}
$$

## Feedforward Neural Network

We apply the weight $W^{(1)}$ coming from the edges between layer 0 and layer 1 and add the biases and then apply the Activation function on the resulting vector coordinate-wise.

$$
x=a^{(0)} \longrightarrow \sigma\left(W^{(1)} a^{(0)}+b^{(1)}\right)
$$

$W^{(1)}$ : Edges between
layer 0 and layer 1
$a^{(0)}$ : input
$b^{(1)}$ : biases applied to layer 1
$\sigma$ : activation function

## Feedforward Neural Network

We will call the output of this computation $a^{(1)}$. This is now represented by the nodes in layer 1 .

$$
x=a^{(0)} \longrightarrow \sigma\left(W^{(1)} a^{(0)}+b^{(1)}\right) \quad a^{(1)}
$$

## Feedforward Neural Network

Repeat.

$W^{(2)}$ : Edges between
layer 1 and layer 2
$a^{(1)}$ : input from layer 1
$b^{(2)}$ : biases applied to layer 2
$\sigma$ : activation function

## Feedforward Neural Network

Until you finish the neural network and get the final output.

$$
\begin{aligned}
& x=a^{(0)} \longrightarrow \sigma\left(W^{(1)} a^{(0)}+b^{(1)}\right) \xrightarrow{a^{(1)}} \sigma\left(W^{(2)} a^{(1)}+b^{(2)}\right) \xrightarrow{a^{(2)}} \quad \sigma\left(W^{(3)} a^{(2)}+b^{(3)}\right) \quad-\cdots \cdots \\
& -\cdots-\cdots-\cdots \quad \sigma\left(W^{(n)} a^{(n-1)}+b^{(n)}\right) \longrightarrow a^{(n)}=y
\end{aligned}
$$

## Training a Neural Network

Now suppose that we are given a binary labeled data as before and we want to use neural network to classify this data.

The advantages of the neural network over the perceptron is that neural network would be able to define a much more complicated decision boundary which ultimately give us more ability to classify data.

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To start working with neural network we initiate the weight of the network randomly and then we test if the output that we obtain from the network matches the label of the input. Most likely, the output obtained this way will not be useful with the initial random weight.

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The process of updating the weights for a feedforward neural network is called backpropagation. Which we will present next.

## Backpropagation

To understand backpropagation we will consider the following simplified neural network:

$z_{i}=\sigma\left(a_{i}\right)$ where $\sigma$ is smooth function
$a_{i}=\sum_{l} u_{i l} z_{l}$

## Backpropagation

To understand backpropagation we will consider the following simplified neural network:


$$
z_{i}=\sigma\left(a_{i}\right) \text { where } \sigma \text { is smooth function }
$$

$$
a_{i}=\sum_{l} u_{i l} z_{l}
$$

Suppose that we have $\left\{\left(x_{i}, y_{i}\right)\right\}^{n}{ }_{i=1}$. We want to train the neural network so that it classifies the data. Suppose we have only have a single output and denote that by $y^{\prime}$.
In other words, $y^{\prime}$ is the answer generated by the network and $y$ is the desired output. For simplicity suppose that the cost function is $C_{0}=\left(y-y^{\prime}\right)^{2}$.

## Backpropagation



## Backpropagation



## Backpropagation



## Backpropagation



## Backpropagation



## Backpropagation



## Backpropagation



This explains the variable dependency.

## Backpropagation



Goal : compute $\frac{\partial C_{0}}{\partial u_{i l}}$
Recall :
$z_{i}=\sigma\left(a_{i}\right)$
$a_{i}=\sum_{l} u_{i l} z_{l}$
We now can take the derivative of $C_{0}$ with respect to a specific weight $u_{i l}$

This explains the variable dependency.

## Backpropagation



## Backpropagation



## Backpropagation



We do not know $\frac{\partial C_{0}}{\partial a_{i}}$ so we call it for now $\delta_{i}$

## Backpropagation



## Backpropagation



## Backpropagation




## Backpropagation



## Backpropagation



## Backpropagation



## Backpropagation



$$
z_{i}=\sigma\left(a_{i}\right)
$$

$u_{j i}$

$$
\frac{\partial C_{0}}{\partial u_{i l}}=\frac{\partial C_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}} \quad \text { where } \quad \frac{\partial a_{i}}{\partial u_{i l}}=z_{l}
$$

$$
\text { Want to compute } \frac{\partial C_{0}}{\partial a_{i}}
$$

$$
\frac{\frac{\partial c_{0}}{\partial a_{i}}}{\frac{\partial a_{j}}{\partial a_{i}}}=\sum_{j} \frac{\partial c_{0}}{\partial a_{j}} \frac{\partial a_{j}}{\partial a_{i}}=\sum_{j} \delta_{j} \frac{\partial a_{j}}{\partial a_{i}}=\sum_{j} \delta_{j} \frac{\partial a_{j}}{\partial a_{i}}
$$

## Backpropagation



## Backpropagation



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## Backpropagation



$$
\frac{\partial c_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} \frac{\partial a_{j}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i}
$$

## Backpropagation



## Backpropagation



## Backpropagation



$$
\begin{array}{ll}
\text { In summary } & \frac{\partial C_{0}}{\partial u_{i l}}=\frac{\partial C_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}} \\
\text { where } \quad & \frac{\partial a_{i}}{\partial u_{i l}}=z_{l} \\
& \delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i}
\end{array}
$$

$$
\begin{aligned}
z_{i} & =\sigma\left(a_{i}\right) \\
a_{i} & =\sum_{l} u_{i l} z_{l} \\
C_{0} & =\left(y-y^{\prime}\right)^{2} .
\end{aligned}
$$

$$
\begin{gathered}
z_{j} \\
\vdots \\
C_{0}
\end{gathered}
$$

## Backpropagation



$$
\begin{array}{ll}
\text { In summary } & \frac{\partial C_{0}}{\partial u_{i l}}=\frac{\partial C_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}} \\
\text { where } \quad & \frac{\partial a_{i}}{\partial u_{i l}}=z_{l} \\
& \delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i}
\end{array}
$$

If we have the $\delta_{j}$ we can compute $\delta_{i}$ hence the name backpropagation

## Backpropagation

Output layer


$$
\frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l}
$$

$$
\begin{equation*}
\delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} \tag{*}
\end{equation*}
$$

$$
\begin{aligned}
z_{i} & =\sigma\left(a_{i}\right) \\
a_{i} & =\sum_{l} u_{i l} z_{l} \\
C_{0} & =\left(y-y^{\prime}\right)^{2} \\
z_{k} & =y^{\prime}
\end{aligned}
$$

## Backpropagation

Output layer


$$
\frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l}
$$

$$
\begin{equation*}
\delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} \tag{*}
\end{equation*}
$$

$$
\begin{aligned}
z_{i} & =\sigma\left(a_{i}\right) \\
a_{i} & =\sum_{l} u_{i l} z_{l} \\
C_{0} & =\left(y-y^{\prime}\right)^{2} . \\
\sigma\left(a_{k}\right) & =z_{k}=y^{\prime}
\end{aligned}
$$

Compute $\delta_{\widehat{\ell}}=\frac{\partial C_{0}}{\partial a_{k}}$

## Backpropagation

Output layer


$$
\frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l}
$$

$$
\begin{aligned}
z_{i} & =\sigma\left(a_{i}\right) \\
a_{i} & =\sum_{l} u_{i l} z_{l}
\end{aligned}
$$

$$
\begin{equation*}
\delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} \tag{*}
\end{equation*}
$$

$$
C_{0}=\left(y-y^{\prime}\right)^{2}
$$

$$
\sigma\left(a_{k}\right)=z_{k}=y^{\prime}
$$

$$
\delta_{k}=\frac{\partial C_{0}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial z_{k}} \frac{\partial z_{k}}{\partial a_{k}}
$$

## Backpropagation

Output layer


$$
\frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l}
$$

$$
\begin{equation*}
\delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} \tag{*}
\end{equation*}
$$

$$
\begin{aligned}
z_{i} & =\sigma\left(a_{i}\right) \\
a_{i} & =\sum_{l} u_{i l} z_{l} \\
C_{0} & =\left(y-y^{\prime}\right)^{2} . \\
\sigma\left(a_{k}\right) & \left.=\left(z_{k}\right)=y^{\prime}\right)
\end{aligned}
$$

$$
\delta_{k}=\frac{\partial C_{0}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial \mathscr{Z}_{k}} \frac{\partial \widetilde{Z_{k}}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial\left(y^{\prime}\right)} \frac{\left.\partial y^{\prime}\right)}{\partial a_{k}}
$$

$$
C_{0}
$$

## Backpropagation

Output layer

$a_{j}$

$$
\begin{align*}
& \frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l} \\
& \delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} \quad(*)  \tag{*}\\
& \delta_{k}=\frac{\partial C_{0}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial z_{k}} \frac{\partial z_{k}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial y^{\prime}} \frac{\partial y^{\prime}}{\partial a_{k}}=\frac{\partial\left(y-y^{\prime}\right)^{2}}{\partial y^{\prime}} \sigma^{\prime}\left(a_{k}\right)
\end{align*}
$$

$$
\begin{gathered}
z_{i}=\sigma\left(a_{i}\right) \\
a_{i}=\sum_{l} u_{i l} z_{l} \\
C_{0}=\left(y-y^{\prime}\right)^{2} \\
\sigma\left(a_{k}\right)=z_{k}=y^{\prime}
\end{gathered}
$$

## Backpropagation

Output layer


$$
\begin{aligned}
& \delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i}(*) \\
& C_{0}=\left(y-y^{\prime}\right)^{2} \\
& \delta_{k}= \frac{\partial C_{0}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial z_{k}} \frac{\partial z_{k}}{\partial a_{k}}=\frac{\left.\partial C_{0}\right)=z_{k}=y^{\prime}}{\partial y^{\prime}} \frac{\partial y^{\prime}}{\partial a_{k}}=\frac{\partial\left(y-y^{\prime}\right)^{2}}{\partial y^{\prime}} \sigma^{\prime}\left(a_{k}\right)=-2\left(y-y^{\prime}\right) \sigma^{\prime}\left(a_{k}\right)
\end{aligned}
$$

## Backpropagation

Output layer


$$
z_{i} \quad u_{j i}
$$

$$
\begin{array}{cc}
\frac{\partial c_{0}}{\partial u_{i l}}=\frac{\partial c_{0}}{\partial a_{i}} \frac{\partial a_{i}}{\partial u_{i l}}=\delta_{i} z_{l} & a_{i}=\sum_{l} u_{i l} z_{l} \\
\delta_{i}=\frac{\partial C_{0}}{\partial a_{i}}=\sum_{j} \delta_{j} u_{j i} \sigma^{\prime}\left(a_{i}\right)=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i} & (*) \\
C_{0}=\left(y-y^{\prime}\right)^{2} . \\
\delta_{k}=\frac{\partial C_{0}}{\partial a_{k}}=\frac{\partial C_{0}}{\partial z_{k}} \frac{\partial z_{k}}{\partial a_{k}}=\frac{\left.\partial C_{0}\right)=z_{k}=y^{\prime}}{\partial y^{\prime}} \frac{\partial y^{\prime}}{\partial a_{k}}=\frac{\partial\left(y-y^{\prime}\right)^{2}}{\partial y^{\prime}} \sigma^{\prime}\left(a_{k}\right)=-2\left(y-y^{\prime}\right) \sigma^{\prime}\left(a_{k}\right)
\end{array}
$$

Knowing $\delta_{k}$, we can compute all the $\delta_{h}$ that comes before it using the formula (*)

## Backpropagation Algorithm

Input a set of examples $\left\{\left(x_{i}, y_{i}\right)\right\}^{n}{ }_{i=1}$
(1) Arbitrary choose the weights randomly
(2) For each $x_{k}$ in the training example set:
(1) Feedforward: Apply $x_{k}$ to the neural network and compute the output $y_{k}^{\prime}$
(2) Compute $\delta_{k}=-2\left(y-y^{\prime}\right) \sigma^{\prime}\left(a_{k}\right)$
(3) Compute each of $\delta_{i}=\sigma^{\prime}\left(a_{i}\right) \sum_{j} \delta_{j} u_{j i}$
(4) Compute $\frac{\partial c_{0}}{\partial u_{i l}}=\delta_{i} z_{l}$
(5) Gradient decent: Update the weights $u_{i l}:=u_{i l}-\mathrm{q} \frac{\partial c_{0}}{\partial u_{i l}}$

It is usually good to initiate the weights to small values.


[^0]:    Note that $d_{i} \geq 0$

