The Backpropagation Algorithm

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b is called a bias term.





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As usual we have to define a cost function and a notion of error.

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(1) Initiate w₁, ..., w_d randomly
(2) keep changing w₁, ..., w_d until hopefully f(w₁, ..., w_d) is minimal

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But how exactly do we change w_1, \ldots, w_d?
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- (2) Repeat until convergence :
 - (1) For every i in range(1,d):

 $(1)w_i \coloneqq w_i - q \frac{\partial f}{\partial w_i}$ (here we do simultaneous update for the parameters w_i)

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Gradient decent asserts that the values of the function f when we update as described above are non-increasing :

 $f(old w_i) \ge f(new w_i)$

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Moreover, for any x_0 on the plane $w^T x + b = 0$ we have

$$b = -w^T x_0$$

$$d = w^{T}(x' - x_{0}) = w^{T}x' - w^{T}x_{0} = w^{T}x' + b$$



$$d = w^T (x' - x_0) = w^T x' - w^T x_0 = w^T x' + b$$

So if we have a point and we want to see where it is located on with respect to the plan, then all we have to do is to plug it in the equation of the plane.



Write

 $d_i = y_i(w^T x_i + b)$

Where (x_i, y_i) is a training example

Note that $d_i \ge 0$



Define

$$error(w, b) \coloneqq -\sum_{M} y_i(w^T x_i + b_0)$$



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We want to apply gradient decent on the function error(w, b)

$$\frac{\partial error(w,b)}{\partial w} = \sum_{M} y_{i} x_{i}$$
$$\frac{\partial error(w,b)}{\partial b} = \sum_{M} y_{i}$$



To train a perceptron

(1) Assign the weights *w* randomly



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$$w_{new} := w_{old} - q \frac{\partial error(w, b)}{\partial w}$$
$$b_{new} := b_{old} - q \frac{\partial error(w, b)}{\partial b}$$

if the examples are linearly separable then the above model classifies the points



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 $error(w, b) \coloneqq -\sum_{M} y_i(w^T x_i + b_0)$

Neural Network

Perceptron is the building block of a neural network. Clearly there are some data that cannot be classified using a single perceptron.

The idea of neural network is to stack together multiple layers of perceptrons in order to be able to learn more complicated functions



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The training of a neural network means to tune the weights in all layers so that the output of the function f matches the label of x. The process of updating the weights for a feedforward neural network is called *backpropagation*.



How do we compute a feedforward neural network on an input x ?

Start with an input $x = a^{(0)}$. In the picture, this is represented by the first layer of nodes. We will call this layer 0.

 $x = a^{(0)}$

We apply the weight $W^{(1)}$ coming from the edges between layer 0 and layer 1 and add the biases and then apply the Activation function on the resulting vector coordinate-wise.

$$x = a^{(0)} \longrightarrow \sigma(W^{(1)}a^{(0)} + b^{(1)})$$

 $W^{(1)}$: Edges between layer 0 and layer 1 $a^{(0)}$: input $b^{(1)}$: biases applied to layer 1 σ : activation function

We will call the output of this computation $a^{(1)}$. This is now represented by the nodes in layer 1.

$$x = a^{(0)} \longrightarrow \sigma(W^{(1)}a^{(0)} + b^{(1)}) \xrightarrow{a^{(1)}}$$

 $W^{(1)}$: Edges between layer 0 and layer 1 $a^{(0)}$: input $b^{(1)}$: biases applied to layer 1 σ : activation function

Repeat.

$$x = a^{(0)} \longrightarrow \sigma(W^{(1)}a^{(0)} + b^{(1)}) \xrightarrow{a^{(1)}} \sigma(W^{(2)}a^{(1)} + b^{(2)}) \xrightarrow{a^{(2)}}$$

 $W^{(2)}$: Edges between layer 1 and layer 2 $a^{(1)}$: input from layer 1 $b^{(2)}$: biases applied to layer 2 σ : activation function

Until you finish the neural network and get the final output.

Now suppose that we are given a binary labeled data as before and we want to use neural network to classify this data.

The advantages of the neural network over the perceptron is that neural network would be able to define a much more complicated decision boundary which ultimately give us more ability to classify data.

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The process of updating the weights for a feedforward neural network is called *backpropagation*. Which we will present next.

To understand backpropagation we will consider the following simplified neural network:



 $z_i = \sigma(a_i)$ where σ is smooth function

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Suppose that we have $\{(x_i, y_i)\}_{i=1}^n$. We want to train the neural network so that it classifies the data. Suppose we have only have a single output and denote that by y'.

In other words, y' is the answer generated by the network and y is the desired output. For simplicity suppose that the cost function is $C_0 = (y - y')^2$.















This explains the variable dependency.



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Backpropagation Algorithm

Input a set of examples $\{(x_i, y_i)\}_{i=1}^n$

- (1) Arbitrary choose the weights randomly
- (2) For each x_k in the training example set:
 - (1) Feedforward: Apply x_k to the neural network and compute the output y'_k
 - (2) Compute $\delta_k = -2(y y')\sigma'(a_k)$
 - (3) Compute each of $\delta_i = \sigma'(a_i) \sum_j \delta_j u_{ji}$
 - (4) Compute $\frac{\partial c_0}{\partial u_{il}} = \delta_i z_l$

(5) Gradient decent : Update the weights $u_{il} := u_{il} - q \frac{\partial c_0}{\partial u_{il}}$

It is usually good to initiate the weights to small values.